Feed-Forward Neural Networks

LATEST SUBMISSION GRADE 85%

A loss function

| 1. | A feedforward neural network has an input layer, 5 hidden layers and an output layer. What is the depth of this neural network? | 1/1 point |
|----|----------------------------------------------------------------------------------------------------------------------------------------|--------------|
| | 6 | |
| | ✓ Correct | |
| | | |
| 2. | During training, the training data specifies the exact form of the hidden layers of a neural network. True | 1/1 point |
| | False | |
| | ✓ Correct | |
| | | |
| 3. | Implement the ReLU activation function using numpy by replacing None in the code bellow. | 0 / 2 points |
| | 1 import numpy as np 2 3 * def ReLU(x): | |
| | 4 5 y = x*(x==0) Run Reset | |
| | Incorrect | |
| | This answer is incorrect. Please refer back to Lesson 1 in this module to review this material. | |
| | | |
| 4. | The main building blocks of a machine learning system are: (Check all that apply.) | 1/1 point |
| | An Optimization Procedure | |
| | ✓ Correct Correct! | |
| | | |

| | ✓ Correct! | |
|----|-------------------------------------------------------------------------------------------------------------|-------------|
| | ✓ A Model | |
| | ✓ Correct Correct! | |
| | Hidden layers | |
| | Output Layers | |
| 5. | Which output unit/loss function pair is usually used for regression tasks that use neural networks? | 0 / 1 point |
| | Linear output units with Mean Squared Error Loss | |
| | Sigmoid output units with Mean Squared Error Loss | |
| | Softmax output units with Cross-Entropy Loss | |
| | Linear output units with Cross-Entropy Loss | |
| | ! Incorrect This answer is incorrect. Please refer back to Lesson 2 in this module to review this material. | |
| | | |
| | ss-entropy loss is used to model the mean of a Gaussian distribution. opx 0px 0px 66px False | 1/1 point |
| | | |
| | ✓ Correct! | |
| 7. | Which of the following might be used as a stopping condition for gradient descent. (Check all that apply.) | 1/1 point |
| | The number of iterations or epochs | |
| | ✓ Correct Correct! | |
| | The magnitude of change in loss function value | |
| | ✓ Correct! | |
| | The magnitude of the change in parameter values | |

| | Correct! | |
|-----|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|
| | ☐ The value of the training loss | |
| 8. | How are neural network bias parameters usually initialized at the beginning of training? Initialized to -1. Initialized to samples from a standard uniform distribution. Initialized to samples from a standard normal distribution. | 1 / 1 point |
| | ✓ Initialized to 0.✓ Correct | |
| 9. | Using all samples to estimate the gradient of the loss function with respect to the parameter results in less than linear return in accuracy of this estimate. True False | 1 / 1 point |
| | ✓ Correct! Correct! | |
| 10. | You are working on a self-driving car project and want to train a neural network to perform traffic sign classification. You collect images with corresponding traffic sign labels, and want to determine the number of frames you will use for training. Given that you have around one million images with labels, what training/validation/testing data split would you use? 20% training, 40% validation, 40% testing. 100% training, 0% validation, 0% testing. 96% training, 2% validation, 2% testing. 60% training, 20% validation, 20% testing. | 1/1 point |
| | ✓ Correct Correct! | |
| 11. | You finish training your traffic sign classifier, and want to evaluate its performance. You compute the classification accuracy on the training, validation, and testing data splits and get the following results: | 2 / 2 points |

| Data Split | Training | Validation | Testing |
|------------|----------|------------|---------|
| Accuracy | 70% | 68% | 67% |

You know that a human has an accuracy of around 98% on the traffic sign classification task. What are things you might try to achieve human level performance? (Check all that apply.)

| | Collect more training data. | |
|-----|---------------------------------------------------------------------------------------------------------------------------------------|-----------|
| | Add regularization to your neural network. | |
| | Train your neural network longer. | |
| | ✓ Correct Correct! | |
| | Add more layers to your neural network. | |
| | ✓ Correct Correct! | |
| 12. | When a neural network overfits the training data, the generalization gap is usually very small. True False | 1/1 point |
| | ✓ Correct Correct! | |
| 13. | Which of the following strategies are used for regularization in neural networks? (Check all that apply.) Dropout | 1/1 point |
| | ✓ Correct Correct! | |
| | ✓ Early Stopping | |
| | ✓ Correct Correct! | |
| | ☐ Training the neural network longer | |
| | ☐ Increasing the number of parameters in the neural network architecture ✓ Norm Penalties | |
| | ✓ Correct Correct! | |
| 14. | Dropout significantly limit the type of neural network models that can be used, and hence is usually used for specific architectures. | 1/1 point |

○ True

| | False | |
|-----|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|
| | ✓ Correct Correct! | |
| 15. | The name convolutional neural networks comes from the fact that these neural networks use a convolution operation instead of general matrix multiplication. True False | 1 / 1 point |
| | ✓ Correct! | |
| 16. | The input to a pooling layer has a width, height and depth of 224x224x3 respectively. The pooling layer has the following properties: • Kernel shape: 2x2 • Stride: 2 What is the width of the output of this pooling layer? | 2 / 2 points |
| | 112 | |
| | ✓ Correct Correct! | |
| 17. | Using convolutions might reduce overfitting, as the number of parameters in convolutional layers is less than the number of parameters in fully connected layers. True False | 1/1 point |
| | ✓ Correct! | |
| | | |